

Notation and Vocabulary for \mathbb{R}^n :

- ▶ One dimension = real-number line = \mathbb{R} .
- ▶ 2-dimensional space = plane = \mathbb{R}^2 . We'll call it "2-space" sometimes.
- ▶ 3-dimensional space = space = \mathbb{R}^3 . We'll call it "3-space".
- ▶ In general, n dimensions = \mathbb{R}^n = n -space.

3-dimensional space is the highest number of dimensions we can readily graph.

Most ideas related to points in 2-space have a natural extension to 3-, or n -, space.

► Distance in 3-space

$$\text{distance} = d(P_1, P_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}.$$

- Just as a circle of radius r centered at (a, b) consists of all points (x, y) that are a distance r away from (a, b) , so

$$(x - a)^2 + (y - b)^2 = r^2,$$

a sphere of radius r centered at (a, b, c) is of the form

$$(x - a)^2 + (y - b)^2 + (z - c)^2 = r^2.$$

Vector Basics

- ▶ **scalar**=quantity described by *magnitude* only.

Examples: area, length, mass, temperature

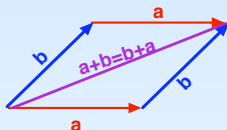
- ▶ **vector**=quantity described by *magnitude* and *direction*.

Examples: wind velocity, force, displacement

- ▶ Represent vectors with arrows
 - ▶ direction of arrow= direction of vector
 - ▶ length of the arrow = magnitude of the vector

Vector Basics

- ▶ Geometry of Vector Addition:



- ▶ **zero vector**, $\vec{0}$ = vector whose initial and terminal points are the same – a vector of length 0.
- ▶ $\vec{0} + \vec{v} = \vec{v} = \vec{v} + \vec{0}$
- ▶ **scalar multiple** $k\vec{v}$ = vector of length $|k| \times$ length of \vec{v} , direction is *the same* as that of \vec{v} if $k > 0$ and the opposite of that of \vec{v} if $k < 0$.
- ▶ $(-1)\vec{v}$ = **the opposite** of \vec{v} ; can write as $-\vec{v}$.

Vector Basics

- ▶ Given any vector $\vec{\mathbf{v}}$, if you position it so that it's initial point is at the origin and it's terminal point is at the point $P(v_1, v_2)$, or in 3-space $P(v_1, v_2, v_3)$, then we call these these coordinates the components of the vector $\vec{\mathbf{v}}$, and write

$$\vec{\mathbf{v}} = \langle v_1, v_2 \rangle \quad \text{or} \quad \vec{\mathbf{v}} = \langle v_1, v_2, v_3 \rangle .$$

- ▶ If we have a vector with initial point P_1 and terminal point P_2 , don't have to re-draw it with its initial point at the origin:

$$\begin{aligned} \overrightarrow{P_1 P_2} &= \langle x_2 - x_1, y_2 - y_1 \rangle \\ \overrightarrow{P_1 P_2} &= \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle . \end{aligned}$$

Vector Basics

- Addition and subtraction are done component-wise:

Example: If $\vec{a} = \langle 3, 0 \rangle$ and $\vec{b} = \langle 2, 2 \rangle$,

$$\vec{a} + \vec{b} = \langle 3, 0 \rangle + \langle 2, 2 \rangle = \langle 5, 2 \rangle$$

$$\vec{a} - \vec{b} = \langle 3, 0 \rangle - \langle 2, 2 \rangle = \langle 1, -2 \rangle .$$

When we write a vector using the notation $\vec{\mathbf{v}} = \langle x, y, z \rangle$, we know that if we choose to draw this vector so that it's initial point is at the origin, it's terminal point is at the point (x, y, z) .

$$\text{Length of vector} = \|\vec{\mathbf{v}}\| = \sqrt{x^2 + y^2 + z^2}.$$

This length is also called *magnitude* and *norm*.

A **unit vector** is a vector of length 1.

- ▶ In 2-space, $\langle 1, 0 \rangle$ and $\langle 0, 1 \rangle$ are unit vectors pointing in the direction of the positive x and y axes.

These are commonly written as

- ▶ $\vec{i} = \langle 1, 0 \rangle$
- ▶ $\vec{j} = \langle 0, 1 \rangle$

Any vector $\langle x, y \rangle$ can also be written $x\vec{i} + y\vec{j}$.

- ▶ In 3-space, we expand on this:

- ▶ $\vec{i} = \langle 1, 0, 0 \rangle$
- ▶ $\vec{j} = \langle 0, 1, 0 \rangle$
- ▶ $\vec{k} = \langle 0, 0, 1 \rangle$

Any vector $\langle x, y, z \rangle$ can also be written $x\vec{i} + y\vec{j} + z\vec{k}$.

Dot Product

- ▶ If $\vec{v} = \langle v_1, v_2 \rangle$ and $\vec{w} = \langle w_1, w_2 \rangle$, then

$$\vec{v} \cdot \vec{w} = \langle v_1, v_2 \rangle \cdot \langle w_1, w_2 \rangle \stackrel{\text{def}}{=} v_1 w_1 + v_2 w_2$$

- ▶ If $\vec{v} = \langle v_1, v_2, v_3 \rangle$ and $\vec{w} = \langle w_1, w_2, w_3 \rangle$, then

$$\vec{v} \cdot \vec{w} = \langle v_1, v_2, v_3 \rangle \cdot \langle w_1, w_2, w_3 \rangle \stackrel{\text{def}}{=} v_1 w_1 + v_2 w_2 + v_3 w_3.$$

- ▶ In general, if $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$ and $\vec{w} = \langle w_1, w_2, \dots, w_n \rangle$, then

$$\vec{v} \cdot \vec{w} = \langle v_1, \dots, v_n \rangle \cdot \langle w_1, \dots, w_n \rangle \stackrel{\text{def}}{=} v_1 w_1 + v_2 w_2 + \dots + v_n w_n.$$

Dot Product

$$\|\vec{\mathbf{v}}\|^2 = \left(\sqrt{v_1^2 + \cdots + v_n^2} \right)^2 = v_1^2 + v_2^2 + \cdots + v_n^2 = \vec{\mathbf{v}} \cdot \vec{\mathbf{v}}.$$

Let $\vec{a} = \langle 3, 5 \rangle$, $\vec{b} = \langle 7, 2 \rangle$, and $\vec{c} = \langle 1, 3, -2 \rangle$.

1. Draw \vec{a} and \vec{b} on the same set of axes. On a separate set of axes, draw \vec{c} .
2. Draw $\vec{a} + \vec{b}$ and $\vec{a} - \vec{b}$.
3. Find $\vec{a} \cdot \vec{b}$, if possible. If it's not possible, why not?
4. Find $\vec{b} \cdot \vec{c}$, if possible. If it's not possible, why not?
5. Is the angle between \vec{a} and \vec{b} acute, orthogonal, or obtuse?
Do (5) without calculating the angle.
6. Find the angle between \vec{a} and \vec{b} .
7. Find two vectors perpendicular to \vec{b} .
8. Find three vectors perpendicular to \vec{c} .