The 8 motions on the square

$$
\left\{R_{0}, R_{90}, R_{180}, R_{270}, H, D, V, D^{\prime}\right\}
$$

and the operation $\circ$ of combining the motions form a system called the dihedral group of order 8 , denoted $D_{4}$.

Below is the Cayley table showing the result of the applying the operation to any 2 elements.

| $\circ$ | $R_{0}$ | $R_{90}$ | $R_{180}$ | $R_{270}$ | $H$ | $D$ | $V$ | $D^{\prime}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $R_{0}$ | $R_{0}$ | $R_{90}$ | $R_{180}$ | $R_{270}$ | $H$ | $D$ | $V$ | $D^{\prime}$ |
| $R_{90}$ | $R_{90}$ | $R_{180}$ | $R_{270}$ | $R_{0}$ | $D^{\prime}$ | $H$ | $D$ | $V$ |
| $R_{180}$ | $R_{180}$ | $R_{270}$ | $R_{0}$ | $R_{90}$ | $V$ | $D^{\prime}$ | $H$ | $D$ |
| $R_{270}$ | $R_{270}$ | $R_{0}$ | $R_{90}$ | $R_{180}$ | $D$ | $V$ | $D^{\prime}$ | $H$ |
| $H$ | $H$ | $D$ | $V$ | $D^{\prime}$ | $R_{0}$ | $R_{90}$ | $R_{180}$ | $R_{270}$ |
| $D$ | $D$ | $V$ | $D^{\prime}$ | $H$ | $R_{270}$ | $R_{0}$ | $R_{90}$ | $R_{180}$ |
| $V$ | $V$ | $D^{\prime}$ | $H$ | $D$ | $R_{180}$ | $R_{270}$ | $R_{0}$ | $R_{90}$ |
| $D^{\prime}$ | $D^{\prime}$ | $H$ | $D$ | $V$ | $R_{90}$ | $R_{180}$ | $R_{270}$ | $R_{0}$ |

## Important Aspects of the Cayley Table for $D_{4}$

1. Closure: No new motions are introduced. If $A, B \in D_{4}$, then $A \circ B \in D_{4}$.
2. Identity: $R_{0}$ acts as an identity motion $R_{0} \circ A=A \circ R_{0}=A$ for all $A \in D_{4}$.
3. Inverse: Every element has an inverse motion that "undoes" what the motion does. For example, $R_{90} \circ R_{270}=R_{270} \circ R_{90}=R_{0}$.
4. Associativity: You can check the table that $(A \circ B) \circ C=A \circ(B \circ C)$ for all $A, B, C \in D_{4}$. This makes sense if you think of the motions as functions, and one motion followed by another as composition.
5. The motions are not commutative. For example, $R_{90} \circ H=D$ but $H \circ R_{90}=D^{\prime}$. But some motions do commute: $R_{90} \circ R_{180}=R_{180} \circ R_{90}=R_{270}$.
6. Although it's not obvious from the table, all of the motions can be obtained by some combination of $R_{90}$ and $H$. In this sense, these two motions generate $D_{4}$.

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